REPORT DOCUMENTATION PAGE

Form Approved OMB No. 0704-0188

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1. REPORT DATE (DD-MM-YYYY)	2. REPORT TYPE	3. DATES COVERED (From - To)		
July 2013	Viewgraph	July 2013- August 2013		
4. TITLE AND SUBTITLE	5a. CONTRACT NUMBER			
Acceleration of PCI and CR algorithms	In-House			
modeling (Briefing Charts)				
		5b. GRANT NUMBER		
		5c. PROGRAM ELEMENT NUMBER		
6. AUTHOR(S)	5d. PROJECT NUMBER			
R. Martin, H. Le, C. Lederman, JL. Cambier				
		5e. TASK NUMBER		
		5f. WORK UNIT NUMBER		
		Q0AE		
7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES)		8. PERFORMING ORGANIZATION REPORT NO.		
Air Force Research Laboratory (AFMC	")	REPORT NO.		
AFRL/RQRS				
1 Ara Drive.				
Edwards AFB CA 93524-7013				
	() () () () () () () () () ()	40.00011000(#1011170010.400011/4/0)		
9. SPONSORING / MONITORING AGENCY		10. SPONSOR/MONITOR'S ACRONYM(S)		
Air Force Research Laboratory (AFMC	-)			
AFRL/RQR		44 000000000000000000000000000000000000		
5 Pollux Drive		11. SPONSOR/MONITOR'S REPORT		
Edwards AFB CA 93524-7048		NUMBER(S)		
		AFRL-RQ-ED-VG-2013-180		

12. DISTRIBUTION / AVAILABILITY STATEMENT

Distribution A: Approved for Public Release; Distribution Unlimited. PA#13398

13. SUPPLEMENTARY NOTES

Viewgraph for the AFOSR Computational Mathematics Program Review, Arlington, VA, 29 July – 1 August 2013.

14. ABSTRACT

We describe enhancements under development for multi-scale methods to be applied to the high-fidelity modeling of spacecraft electric propulsion systems and their environment. Multiple challenges in multi-scale integration, statistical accuracy, and physical modeling are addressed through a variety of innovative numerical methods and mathematical approaches. We emphasize the advances made on a specialized multi-scale time-stepping integrator for finite-Larmor radius particle trajectories, accelerated collisional-radiative non-equilibrium ionization kinetics through Boltzmann equilibrated level groups, and a novel approach to dynamic phase-space reconstruction which can be used to resolve the problems of multi-scale statistics in particle-based kinetic simulations.

15. SUBJECT TERMS

16. SECURITY CLASSIFICATION OF:		17. LIMITATION OF ABSTRACT	18. NUMBER OF PAGES	19a. NAME OF RESPONSIBLE PERSON Jean-Luc Cambier	
a. REPORT	b. ABSTRACT	c. THIS PAGE	SAR	76	19b. TELEPHONE NO (include area code)
Unclassified	Unclassified	Unclassified	SAK		661-525-5649

ACCELERATION OF PIC AND CR ALGORITHMS FOR HIGH FIDELITY IN-SPACE PROPULSION MODELING

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AFOSR Computational Math Annual Review, Arlington VA, July 29, 2013





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OUTLINE



- Introduction
- 2 EFFICIENT ELECTRON PUSH
- 3 ACCELERATED COLLISIONAL-RADIATIVE MODELS
- 4 PARTICLE REMAPPING
- **5** FUTURE WORK

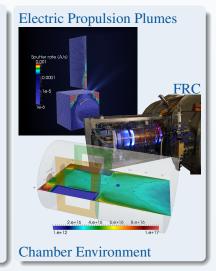


SPACECRAFT PLASMA MODELING CHALLENGES



Spacecraft Propulsion Relevant Plasma:

- From hall thrusters to plumes and fluxes on components
- Complex reaction physics i.e.
 Discharge and Breakdown in FRC
- Relevant Densities often Span6+ Orders of Magnitude
- Spatial scales of interest span μm-100m range





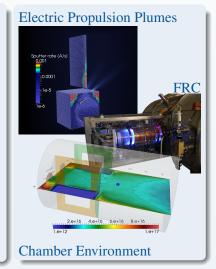
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Solution?
Multi-Scale and Multi-Physics
Adaptive Algorithms







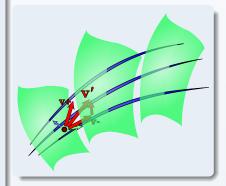
$$v^{-} = v(t - \Delta t/2) + \frac{q\Delta t}{2m}E(t)$$

$$v' = v^{-} + \frac{q\Delta t}{2m}v^{-} \times B(t)$$

$$v^{+} = v^{-} + \frac{\frac{q\Delta t}{2m}}{1 + \left(\frac{q\Delta t}{2m}|B|\right)}v' \times B(t)$$

$$v(t + \Delta t/2) = v^{+} + \frac{q\Delta t}{2m}E(t)$$

$$r(t + \Delta t) = r(t) + \Delta tv(t + \Delta t/2)$$







Boris Push:

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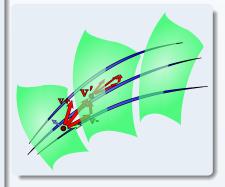
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• Leap-Frog in r & v







$$v^{-} = v(t - \Delta t/2) + \frac{q\Delta t}{2m}E(t)$$

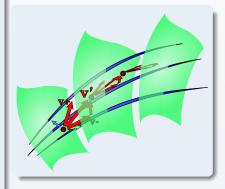
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- Leap-Frog in r & v
- Energy Conservation only via Interpolation in Time







$$v^{-} = v(t - \Delta t/2) + \frac{q\Delta t}{2m}E(t)$$

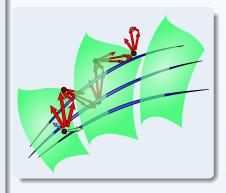
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- Leap-Frog in r & v
- Energy Conservation only via Interpolation in Time
- Numerically Stable but Drifts and Fails when $\Delta t > \omega_c/2$







$$v^{-} = v(t - \Delta t/2) + \frac{q\Delta t}{2m}E(t)$$

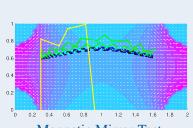
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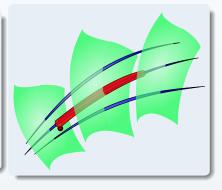
Magnetic Mirror Test





Gyrokinetic Push:

- Effective for High-B Plasma (i.e. Magnetic-Fusion)
- Assumes $\lambda_c \ll dx$
- Looses Phase Information
- Assumes Phase-Scatter Diffusion Negligible

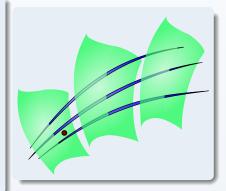






B-Frame Push:

• Coordinates Rotated and Aligned to *B*-Field

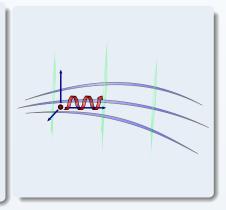






B-Frame Push:

- Coordinates Rotated and Aligned to *B*-Field
- Motion Decomposed into Rotation and Drift
- Exact Solution in Constant Field

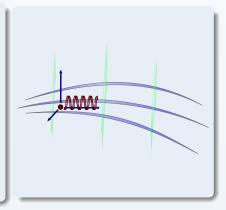






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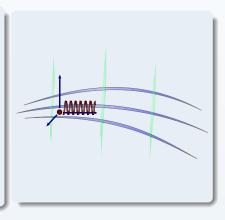




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What about Variable Fields?

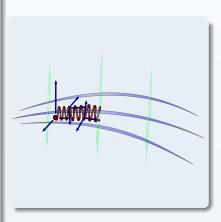






B-Frame Push in Variable Fields:

 Consistent Solution Recovered with Multiple Steps

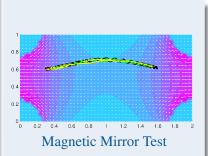






B-Frame Push in Variable Fields:

- Consistent Solution Recovered with Multiple Steps
- Convergence Order is Low

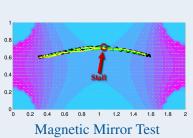






B-Frame Push in Variable Fields:

- Consistent Solution Recovered with Multiple Steps
- Convergence Order is Low
- Solution Stalls when $dt > \omega_c$







B-Frame Push in Variable Fields:

- Consistent Solution Recovered with Multiple Steps
- Convergence Order is Low
- Solution Stalls when $dt > \omega_c$
- Consider the Push in B-Aligned Coordinates...
- No Mechanism for $v_{\perp} \rightarrow v_{\parallel}$ in Step? (No Bounce in Magnetic Mirror?)
- Variable \vec{B} and \vec{E} via Taylor Series?

$$\Delta \vec{v} = \mathbf{D}_{0} \cdot \vec{v} + \frac{q\Delta t}{m} \mathbf{D}_{1} \cdot \vec{E}$$

$$\Delta \vec{x} = \mathbf{D}_{1} \cdot \vec{v} \Delta t + \frac{q\Delta t^{2}}{m} \mathbf{D}_{2} \cdot \vec{E}$$

$$\mathbf{D}_{k} = \hat{\mathbf{R}}^{-1} \cdot \Delta_{k} \cdot \hat{\mathbf{R}}$$

$$\Delta_{v}^{s} = \underbrace{\begin{pmatrix} -c_{0} & s_{0} & 0 \\ -s_{0} & c_{0} & 0 \end{pmatrix} \cdot \begin{bmatrix} v_{s} \\ v_{s} \end{bmatrix}}_{\Delta_{s}} + \underbrace{\begin{pmatrix} -c_{1} & c_{1} & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{bmatrix} a_{s} \\ a_{s} \end{bmatrix}}_{\Delta_{s}}$$

$$\Delta_{x}^{g} = \underbrace{\begin{pmatrix} -c_{1} & c_{1} & 0 \\ -c_{1} & s_{1} & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{bmatrix} v_{s} \Delta t \\ v_{s} \Delta t \end{bmatrix}}_{\Delta_{s}} + \underbrace{\begin{pmatrix} c_{2} & -c_{2} & 0 \\ 0 & 0 & \frac{1}{2} \end{pmatrix}}_{\Delta_{s}} \cdot \begin{bmatrix} a_{s} \Delta t^{2} \\ a_{s} \Delta t^{2} \end{bmatrix}}_{\Delta_{s}}$$





B-Frame Push in Variable Fields:

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But even \hat{R} depends on \vec{B} (And is Partially Arbitrary!)

$$\Delta \vec{v} = \mathbf{D}_{0} \cdot \vec{v} + \frac{q\Delta t}{m} \mathbf{D}_{1} \cdot \vec{E}$$

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$$\Delta^{x} = \begin{pmatrix} -c_{1} & s_{1} & 0 \\ -s_{0} & s_{0} & 0 \end{pmatrix} \cdot \begin{bmatrix} v_{i}\Delta t^{2} \\ v_{i}\Delta t^{2} \end{bmatrix} + \begin{pmatrix} c_{2} & -c_{2} & 0 \\ 0 & 0 & \frac{1}{2} \end{pmatrix} \cdot \begin{bmatrix} a_{i}\Delta t^{2} \\ a_{i}\Delta t^{2} \\ a_{i}\Delta t^{2} \end{bmatrix}$$

$$\Delta_{k} = \begin{pmatrix} -c_{1} & s_{1} & 0 \\ -c_{1} & s_{1} & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{bmatrix} a_{i}\Delta t^{2} \\ a_{i}\Delta t^{2} \\ a_{i}\Delta t^{2} \end{bmatrix}$$





B-Frame Push in Variable Fields (cont.):

• Push as Explicit Matrix Operator: (For now Ignoring \vec{E})

$$X_+ = M \cdot X_0$$

$$\mathbb{X}_{+} = \begin{bmatrix} \vec{x}_{+} \\ \vec{v}_{+} \end{bmatrix} = \begin{bmatrix} \vec{x_{0}} + \Delta \vec{x} \\ \vec{v_{0}} + \Delta \vec{v} \end{bmatrix} = \underbrace{\begin{bmatrix} \mathbb{I} & \mathbf{D_{1}} \\ \mathbf{0} & \mathbb{I} + \Delta \mathbf{n} \mathbf{D_{0}} \end{bmatrix}}_{\mathbb{M}} \cdot \begin{bmatrix} \vec{x}_{0} \\ \vec{v}_{0} \end{bmatrix}$$





B-Frame Push in Variable Fields (cont.):

- Push as Explicit Matrix Operator: (For now Ignoring \vec{E})
- What's Known about M:
 - Reversible through Time Inversion...
 - M⁻¹ Must Exist
 - \mathbb{M} is a 1:1 Map of $\mathbb{X}_0 \to \mathbb{X}_+$
 - M is Unique (Even if \hat{R} was Not...)
 - If M is Unique, Elements are Unique
 - M is Constant if \vec{B} is Constant

$$\begin{bmatrix} \vec{x_0} + \Delta \vec{x} \end{bmatrix} \begin{bmatrix} \mathbb{I} & \mathbf{D}_1 \end{bmatrix} \begin{bmatrix} \vec{x}_0 \end{bmatrix}$$

$$\mathbb{X}_{+} = \begin{bmatrix} \vec{x}_{+} \\ \vec{v}_{+} \end{bmatrix} = \begin{bmatrix} \vec{x_{0}} + \Delta \vec{v} \\ \vec{v_{0}} + \Delta \vec{v} \end{bmatrix} = \underbrace{\begin{bmatrix} \mathbb{I} & \mathbf{D_{1}} \\ \mathbf{0} & \mathbb{I} + \Delta t \mathbf{D_{0}} \end{bmatrix}}_{\mathbb{M}} \cdot \begin{bmatrix} \vec{x}_{0} \\ \vec{v}_{0} \end{bmatrix}$$

 $X_+ = M \cdot X_0$





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- What's Known about M:
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 - If M is Unique, Elements are Unique
 - \mathbb{M} is Constant if \vec{B} is Constant

Hypothesis:

Elements of M Vary Smoothly, $\vec{x} \in \vec{x}_{Ngbh}$

(Assuming \vec{B} Varies Smoothly with \vec{x})

$$[\vec{x_0} + \Delta \vec{x}]$$
 [I D₁] $[\vec{x_0}]$

$$\mathbb{X}_{+} = \begin{bmatrix} \vec{x}_{+} \\ \vec{v}_{+} \end{bmatrix} = \begin{bmatrix} \vec{x_{0}} + \Delta \vec{x} \\ \vec{v_{0}} + \Delta \vec{v} \end{bmatrix} = \underbrace{\begin{bmatrix} \mathbb{I} & \mathbf{D_{1}} \\ \mathbf{0} & \mathbb{I} + \Delta t \mathbf{D_{0}} \end{bmatrix}}_{\mathbb{M}} \cdot \begin{bmatrix} \vec{x}_{0} \\ \vec{v_{0}} \end{bmatrix}$$

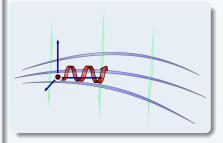
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B-Frame Push in Variable Fields (cont.):

• Assuming \vec{B} varies Periodically in ω_c and Linearly in multiples $N \times \omega_c$...?

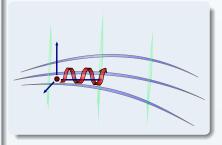






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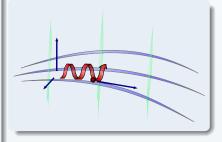




B-Frame Push in Variable Fields (cont.):

- Assuming \vec{B} varies Periodically in ω_c and Linearly in multiples $N \times \omega_c$...?
- Elements of M take Form:

$$m_{ij} = \overline{m}_{ij} + \frac{n\delta t}{\Delta t} \Delta m_{ij}^{[slow]} + cos(\omega n\delta t) \Delta m_{ij}^{[c]} + sin(\omega n\delta t) \Delta m_{ij}^{[s]}$$





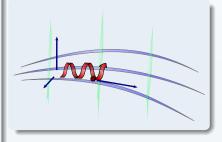


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• Coefficients, Δm_{ij} , can be Sampled using Original Push with $\Delta t = [0, \pi/4, 3\pi/4, 2\pi n]\omega_c$





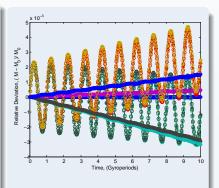


B-Frame Push in Variable Fields (cont.):

- Assuming \vec{B} varies Periodically in ω_c and Linearly in multiples $N \times \omega_c$...?
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- Coefficients, Δm_{ij} , can be Sampled using Original Push with $\Delta t = [0, \pi/4, 3\pi/4, 2\pi n]\omega_c$
- Comparison of Fit and Sampled M from Magnetic Mirror



Closed Circle - Original Push Stepping m_{ij} Open Circle - Estimated m_{ij} from Sampling





Compounded Push Operator:

• Uniform Field Push can be Subdivided





Compounded Push Operator:

• Uniform Field Push can be Subdivided

$$\mathbb{X}(t + \Delta t) = \mathbb{M}(\Delta t) \cdot \mathbb{X}_0$$
$$= \mathbb{M}^{(p-1)}(\Delta t/p) \cdot \mathbb{X}_0$$





Compounded Push Operator:

- Uniform Field Push can be Subdivided
- Can be Written as Product of δt Substeps

$$\mathbb{X}(t + \Delta t) = \mathbb{M}(\Delta t) \cdot \mathbb{X}_0$$

$$= \mathbb{M}^{(p-1)}(\Delta t/p) \cdot \mathbb{X}_0$$

$$= \prod_{k=0}^{p-1} \mathbb{M}^{[k]}(\delta t) \cdot \mathbb{X}_0$$





Compounded Push Operator:

- Uniform Field Push can be Subdivided
- Can be Written as Product of δt Substeps
- Also True if $\mathbb{M}^{[k]}$ varies with t Equivalent to Explicit Stepping with Smaller Δt

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Compounded Push Operator:

- Uniform Field Push can be Subdivided
- Can be Written as Product of δt Substeps
- Also True if $\mathbb{M}^{[k]}$ varies with t Equivalent to Explicit Stepping with Smaller Δt
- Estimator for M^[k] Reduces Field Evaluations, but not Push Multiplier Operations...

$$\mathbb{X}(t + \Delta t) = \mathbb{M}(\Delta t) \cdot \mathbb{X}_0$$

$$= \mathbb{M}^{(p-1)}(\Delta t/p) \cdot \mathbb{X}_0$$

$$= \prod_{k=0}^{p-1} \mathbb{M}^{[k]}(\delta t) \cdot \mathbb{X}_0$$





Operation Reduction:

• Given the Gyro-Estimated Compounded Operator $\widetilde{\mathbb{M}}$...

$$\widetilde{\mathbb{M}} = \prod_{k=0}^{p-1} \mathbb{M}^{[k]}$$





Operation Reduction:

- Given the Gyro-Estimated Compounded Operator $\widetilde{\mathbb{M}}$...
- Can be Split into Mean and Deviation

$$\begin{split} \widetilde{\mathbb{M}} &= \prod_{k=0}^{p-1} \mathbb{M}^{[k]} \\ &= \prod_{k=0}^{p-1} \left(\overline{\mathbb{M}} \! + \! \Delta \mathbb{M}^{[k]} \right) \end{split}$$





Operation Reduction:

- Given the Gyro-Estimated Compounded Operator M...
- Can be Split into Mean and Deviation
- The Operator is Linearized around $\overline{\mathbb{M}}$

$$\begin{split} \widetilde{\mathbb{M}} &= \prod_{k=0}^{p-1} \mathbb{M}^{[k]} \\ &= \prod_{k=0}^{p-1} \left(\overline{\mathbb{M}} + \Delta \mathbb{M}^{[k]} \right) \\ &= \prod_{k=0}^{p-1} \left(\mathbb{L} \Delta \mathbb{R} + \Delta \mathbb{M}^{[k]} \right) \end{split}$$





- Given the Gyro-Estimated Compounded Operator $\widetilde{\mathbb{M}}$...
- Can be Split into Mean and Deviation
- The Operator is Linearized around $\overline{\mathbb{M}}$

$$\begin{split} \widetilde{\mathbb{M}} &= \prod_{k=0}^{p-1} \mathbb{M}^{[k]} \\ &= \prod_{k=0}^{p-1} \left(\overline{\mathbb{M}} + \Delta \mathbb{M}^{[k]} \right) \\ &= \mathbb{L} \left[\prod_{k=0}^{p-1} \left(\Lambda + \mathbb{R} \Delta \mathbb{M}^{[k]} \mathbb{L} \right) \right] \mathbb{R} \end{split}$$





- Given the Gyro-Estimated Compounded Operator M...
- Can be Split into Mean and Deviation
- The Operator is Linearized around $\overline{\mathbb{M}}$
- And Assuming $||\Lambda|| \gg ||\mathbb{R}\Delta\mathbb{M}^{[k]}\mathbb{L}||$

$$\begin{split} \widetilde{\mathbb{M}} &= \prod_{k=0}^{p-1} \mathbb{M}^{[k]} \\ &= \prod_{k=0}^{p-1} \left(\overline{\mathbb{M}} + \Delta \mathbb{M}^{[k]} \right) \\ &= \mathbb{L} \left[\prod_{k=0}^{p-1} \left(\Lambda + \mathbb{R} \Delta \mathbb{M}^{[k]} \mathbb{L} \right) \right] \mathbb{R} \\ &= \mathbb{L} \left[\Lambda^{(p-1)} + \sum_{k=0}^{p-2} \left(\Lambda^{(p-2)-k} \mathbb{R} \Delta \mathbb{M}^{[k]} \mathbb{L} \Lambda^k \right) + O(\Delta \mathbb{M}^2) \right] \mathbb{R} \end{split}$$





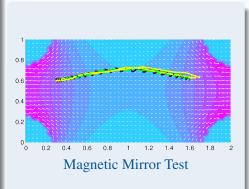
- Given the Gyro-Estimated Compounded Operator $\widetilde{\mathbb{M}}$...
- Can be Split into Mean and Deviation
- The Operator is Linearized around M̄
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- Summations to Series Solution for Linear and Oscillatory Parts of $\Delta M \rightarrow$ Direct Eval of m_{ij}

$$\begin{split} \widetilde{\mathbb{M}} &= \prod_{k=0}^{p-1} \mathbb{M}^{[k]} \\ &= \prod_{k=0}^{p-1} \left(\overline{\mathbb{M}} + \Delta \mathbb{M}^{[k]} \right) \\ &= \mathbb{L} \left[\prod_{k=0}^{p-1} \left(\Lambda + \mathbb{R} \Delta \mathbb{M}^{[k]} \mathbb{L} \right) \right] \mathbb{R} \\ &= \mathbb{L} \left[\Lambda^{(p-1)} + \sum_{k=0}^{p-2} \left(\Lambda^{(p-2)-k} \mathbb{R} \Delta \mathbb{M}^{[k]} \mathbb{L} \Lambda^k \right) + O(\Delta \mathbb{M}^2) \right] \mathbb{R} \\ &m_{ij} \approx \mathbb{L} \left[\lambda_i^{(p-1)} + \lambda_i^{(p-2)} \mathbb{Q}_{ij} \sum_{k=0}^{p-2} \left[f_Q(k) \lambda_{j \setminus i}^k \right] \right] \mathbb{R} \\ &\approx \mathbb{L} \left[\lambda_i^{(p-1)} + \lambda_i^{(p-2)} \mathbb{Q}_{ij} \left\{ \sum_{j=0}^{p-2} \sum_{k=0}^{k \setminus k} \lambda_{j \setminus i}^k \right\} \right] \mathbb{R} \end{split}$$





- Given the Gyro-Estimated Compounded Operator $\widetilde{\mathbb{M}}$...
- Can be Split into Mean and Deviation
- The Operator is Linearized around $\overline{\mathbb{M}}$
- And Assuming $||\Lambda|| \gg ||\mathbb{R}\Delta\mathbb{M}^{[k]}\mathbb{L}||$
- Summations to Series Solution for Linear and Oscillatory Parts of ΔM → Direct Eval of m_{ii}





CR Modeling for Atomic Hydrogen



Elementary processes (electron-impact only)

Collisional excitation/deexcitation

$$H(i) + e^- \leftrightarrow H(j) + e^-$$

Collisional ionization/recombination

$$H(i) + e^- \leftrightarrow H^+ + 2e^-$$

Bound-bound radiative transition

$$H(i) + h\nu \leftarrow H(j)$$



RATE EQUATIONS



Rate Equation

$$K_{ji}^{rad.} = A_{ji}, \quad K_{ji}^{coll.} = N_e \int_{E_{ij}}^{\infty} \sigma_{ij}(\varepsilon) v f(\varepsilon) d\varepsilon$$
$$\frac{dN_i}{dt} = \sum_{R \in \mathbf{R} \times \mathbf{n}} \sum_{j \neq i} (K_{ij}^R N_j - K_{ji}^R N_i)$$
$$dN_i = \sum_{j \neq i} \tilde{\mathbf{K}}_{ij} N_j - \tilde{\mathbf{J}}_i \circ N_i$$

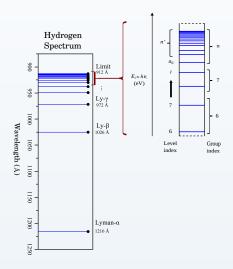
Implicit formulation

$$dN_j = \mathbb{A}_{ij}^{-1} \left[\sum_{j \neq i} \tilde{\mathbf{K}}_{ij} N_j - \tilde{\mathbf{J}}_i \circ N_i \right]$$



LEVEL GROUPING







LEVEL GROUPING



n,m: bin indices; i,j: level indices

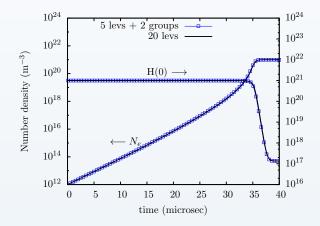
Model	Cons. vars.	Size	Lev. Pop.
Full CR	N_i	$N_{ m level}$	
Reduced CR	$\Sigma_n = \sum N_i$	$N_{ m group}$	$N_{i \in n} = \frac{g_i \Sigma_n}{\sum_{j \in n} g_j}$
(Uniform)	i∈n		
Reduced CR	N_{n_0}	$2 \times N_{\rm group}$	$N_{i \in n} = rac{g_i N_{n_0} e^{-\Delta E_i/kT_n}}{g_{n_0}}$ or $N_{i \in n} = rac{g_i \Sigma_n' e^{-\Delta E_i/kT_n}}{\mathcal{Q}_n'}$
(Boltzmann)	$\Sigma_n' = \sum N_i$		or $N_{i \in n} = \frac{g_i \Sigma_n' e^{-\Delta E_i/kT_n}}{Q_n'}$
	i∈n′		



ISOTHERMAL HEATING TEST ($T_e = 3 \text{ eV}$)



Comparison of ground state and electron number densities

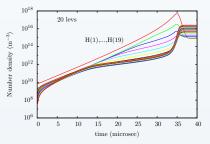


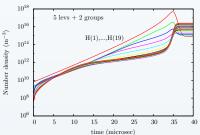


ISOTHERMAL HEATING TEST ($T_e = 3 \text{ eV}$)



Comparison of excited states number densities

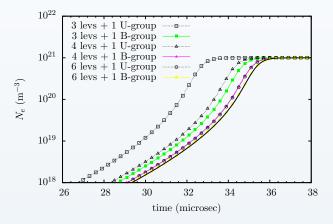






UNIFORM VS. BOLTZMANN

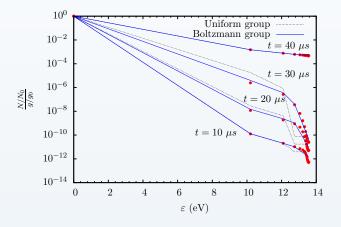






UNIFORM VS. BOLTZMANN









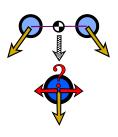
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Numerous Previous Merge Methods:

• 2:1 - Cannot Conserve Energy (Lapenta & Brackbill, JCP 1994)



$$w_m = \sum_i w_i \\ \vec{v}_m = \sum_i w_i \vec{v}_i / w_m$$

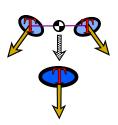
$$w_m v_m^2 < \sum w_i v_i^2$$
!!!





Numerous Previous Merge Methods:

- 2:1 Cannot Conserve Energy (Lapenta & Brackbill, JCP 1994)
- Complex Macro-particles with Internal Energy (Hewett, JCP 2003)



$$\begin{split} w_m &= \sum w_i, \quad \vec{v}_m = \sum w_i \vec{v}_i / w_m \\ T_m^{(int)} &= \left(\sum w_i T_i^{(int)} + \sum w_i v_i^2 - w_m v_m^2\right) / w_m \\ w_m \left(v_m^2 + T_m^{(int)}\right) &= \sum \left(w_i v_i^2 + w_i T_i^{(int)}\right) \checkmark \end{split}$$

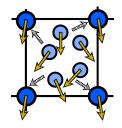
Particle Push with $T^{(int)}$?... Split if $(T^{(int)})^{1/2} \gg v_m$?... In What Coord-System?...





Numerous Previous Merge Methods:

- 2:1 Cannot Conserve Energy (Lapenta & Brackbill, JCP 1994)
- Complex Macro-particles with Internal Energy (Hewett, JCP 2003)
- Merge to Grid
 (Assous et al., JCP 2003, Welch et al., JCP 2007)



Conserve Arbitrary Moments to Grid

Not Explicitly Conserved Lost? Entropy Generation? Shape Functions? Grid Dependence?



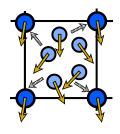




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 (Assous et al., JCP 2003, Welch et al., JCP 2007)

All Introduce Significant Error and/or Complexity



Conserve Arbitrary Moments to Grid

Not Explicitly Conserved Lost? Entropy Generation? Shape Functions? Grid Dependence?





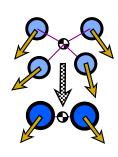
CONSERVATIVE MERGE



Merge to Pair \rightarrow DOF for Conservation:

- (n+2):2 yields Exact Mass,
 Momentum, and Kinetic Energy
 Conservation
- Applied Spatially also Shown to Conserve Electrostatic Energy
- Though Energy Conserving, Still Thermalizes VDF

(AFOSR Review 2006)



$$\begin{split} w_m &= \sum_i^{(n+2)} w_i \\ \overline{\vec{v}} &= \left(\sum_i^{(n+2)} w_i \vec{v}_i\right) / w_m \\ \overline{V^2} &= \left(\sum_i^{(n+2)} w_i \left(\vec{v}_i - \overline{\vec{v}}\right)^2\right) / w_m \\ w_{(a/b)} &= w_m / 2 \\ \vec{v}_{(a/b)} &= \overline{\vec{v}} \pm \hat{\mathcal{R}} \sqrt{\overline{V^2}} \\ \left(\operatorname{Similarly:} \vec{x}_{(a/b)} &= \overline{\vec{x}} \pm \hat{\mathcal{R}} \sqrt{\overline{X^2}} \right) \end{split}$$



Conservative Merge



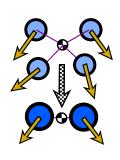
Merge to Pair \rightarrow DOF for Conservation:

- (n+2):2 yields Exact Mass,
 Momentum, and Kinetic Energy
 Conservation
- Applied Spatially also Shown to Conserve Electrostatic Energy
- Though Energy Conserving, Still Thermalizes VDF

(AFOSR Review 2006)

Selection of Near Neighbors in VDF Limits Thermalization

(≈ Near Neighbor Pairs in 2:1 Merges that Limit Numerical Cooling)



$$\begin{aligned} w_m &= \sum_i^{(n+2)} w_i \\ \overline{v} &= \left(\sum_i^{(n+2)} w_i \overrightarrow{v_i}\right) / w_m \\ \overline{V^2} &= \left(\sum_i^{(n+2)} w_i \left(\overrightarrow{v_i} - \overrightarrow{v}\right)^2\right) / w_m \\ w_{(a/b)} &= w_m / 2 \\ \overline{v}_{(a/b)} &= \overline{v} \pm \hat{\mathcal{R}} \sqrt{\overline{V^2}} \\ \left(\text{Similarly: } \overrightarrow{x}_{(a/b)} &= \overline{x} \pm \hat{\mathcal{R}} \sqrt{\overline{X^2}}\right) \end{aligned}$$







Phase-Space Decomposition

• Given a Set of Particles...







Phase-Space Decomposition

- Given a Set of Particles...
- Particles Binned in Octants

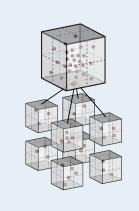






Phase-Space Decomposition

- Given a Set of Particles...
- Particles Binned in Octants
- Octants Recursively Sub-Divided

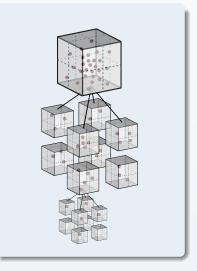






Phase-Space Decomposition

- Given a Set of Particles...
- Particles Binned in Octants
- Octants Recursively Sub-Divided
- Recursion Halted at 1-Particle/Bin or Other Criteria such as Bin-Density



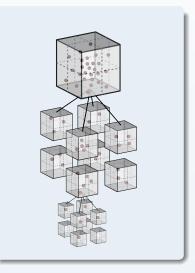




Phase-Space Decomposition

- Given a Set of Particles...
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- Recursion Halted at 1-Particle/Bin or Other Criteria such as Bin-Density

Restricts Phase-Space Diffusion to
Within Local Bins

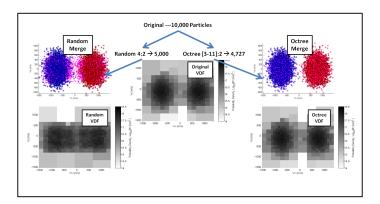




OD-MERGE EXAMPLES



Comparison of Random vs. Octree Merge Partner Selection (Note: Mass, Momentum, and Kinetic Energy Both Exactly Conserved)

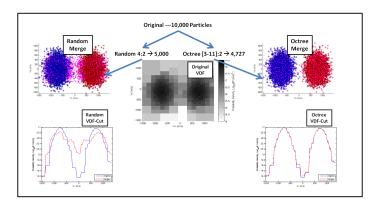




OD-MERGE EXAMPLES



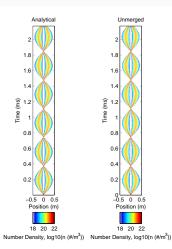
Comparison of Random vs. Octree Merge Partner Selection (Note: Mass, Momentum, and Kinetic Energy Both Exactly Conserved)







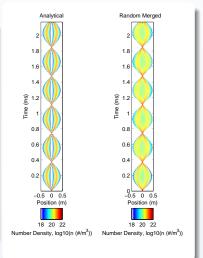
- 6000 Unmerged Particles
- Reproduces 3-4 Orders of Magnitude







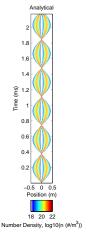
- 6000 Unmerged Particles
- Reproduces 3-4 Orders of Magnitude
- Random Merge -> Thermalization
- 3000 First Point, 1500 First Cross
- Bi-Maxwellian Specifically Difficult

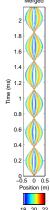






- 6000 Unmerged Particles
- Reproduces 3-4 Orders of Magnitude
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- Bi-Maxwellian Specifically Difficult
- Octree Merge Significantly Better







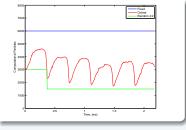


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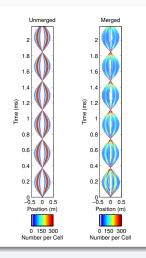
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- Merge & Split Adapts Particle Count







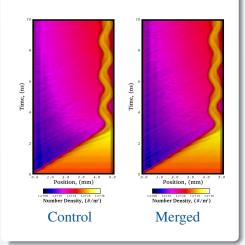
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- Octree Merge Significantly Better
- Merge & Split Adapts Particle Count
- Computational Particles per Cell Vastly Different







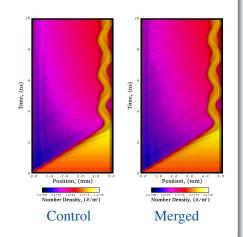
- Full 3D Electrostatic-PIC
- Averaged to 1D XT-Plot







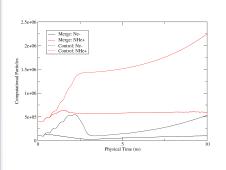
- Full 3D Electrostatic-PIC
- Averaged to 1D XT-Plot
- 250V Cathode → Anode
- MCC-Ionization Collisions
- Secondary Emission at Cathode







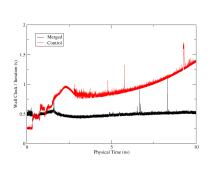
- Full 3D Electrostatic-PIC
- Averaged to 1D XT-Plot
- 250V Cathode \rightarrow Anode
- MCC-Ionization Collisions
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- Chain-Branching Needs Merge







- Full 3D Electrostatic-PIC
- Averaged to 1D XT-Plot
- 250V Cathode → Anode
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- Secondary Emission at Cathode
- Chain-Branching Needs Merge
- Merge Overhead Rapidly Negligible

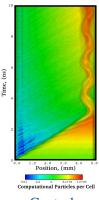






DC-Diode Test Case:

- Full 3D Electrostatic-PIC
- Averaged to 1D XT-Plot
- 250V Cathode → Anode
- MCC-Ionization Collisions
- Secondary Emission at Cathode
- Chain-Branching Needs Merge
- Merge Overhead Rapidly Negligible



Control

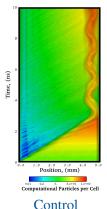
Merged

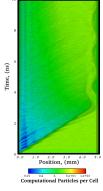




DC-Diode Test Case:

- Full 3D Electrostatic-PIC
- Averaged to 1D XT-Plot
- 250V Cathode \rightarrow Anode
- MCC-Ionization Collisions
- Secondary Emission at Cathode
- Chain-Branching Needs Merge
- Merge Overhead Rapidly Negligible
- Merge: Parts/Cell Much Reduced



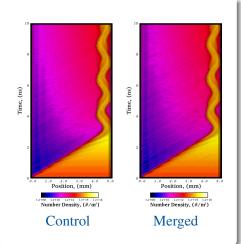


Merged





- Full 3D Electrostatic-PIC
- Averaged to 1D XT-Plot
- 250V Cathode → Anode
- MCC-Ionization Collisions
- Secondary Emission at Cathode
- Chain-Branching Needs Merge
- Merge Overhead Rapidly Negligible
- Merge: Parts/Cell Much Reduced
- Despite Identical Densities





AFRL/RQRS M&S FUTURE WORK

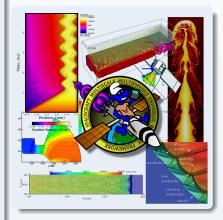


Integrate R&D w/ Production TODO:

- High-Order Fluid/MHD GPU Models (Le/Cole*/Bilyeu PhD Research)
- GPU Accelerated Chemical Kinetics / CR Ar-Ne-Xe-Molecular Models
 (Le/Cole*/Kapper* PhD Research)
- Phase-Space Reconstruction/Vlasov (Martin/Bilyeu/TBD)
- Implicit / Multiscale GPU-Accelerated PIC

(Lederman/Gimelsheins/Martin/TBD)

*Note: Former Co-op Student Work to be Integrated into Framework







Thank You

Questions?